# Statistical Models & Computing Methods

### Lecture 1: Introduction



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School of Mathematical Sciences, Peking University

September 11, 2023

- ► Class times:
  - ► Monday 1:00-2:50pm, Odd Friday 3:10-5:00pm
  - ► Science Classroom Building, Room 406
- ► Instructor:
  - ► Cheng Zhang: chengzhang@math.pku.edu.cn
- ► Teaching assistants:
  - ► Tianyu Xie: tianyuxie@pku.edu.cn
  - ► Ziheng Cheng: alex-czh@stu.pku.edu.cn
- ► Tentative office hours:
  - ▶ 315 Building No.20
  - ► Thursday 3:00-5:00pm or by appointment
- ► Website:

https://zcrabbit.github.io/courses/smcm-f23.html



- ► A branch of mathematical sciences focusing on efficient numerical methods for statistically formulated problems
- ► The focus lies on computer intensive statistical methods and efficient modern statistical models.
- Developing rapidly, leading to a broader concept of computing that combines the theories and techniques from many fields within the context of statistics, mathematics and computer sciences.



Goals 4/35

- ▶ Become familiar with a variety of modern computational statistical techniques and knows more about the role of computation as a tool of discovery
- ▶ Develop a deeper understanding of the mathematical theory of computational statistical approaches and statistical modeling.
- ▶ Understand what makes a good model for data.
- ▶ Be able to analyze datasets using a modern programming language (e.g., python).



Textbook 5/35

▶ No specific textbook required for this course

- ▶ Recommended textbooks:
  - ► Givens, G. H. and Hoeting, J. A. (2005) Computational Statistics, 2nd Edition, Wiley-Interscience.
  - ► Gelman, A., Carlin, J., Stern, H., and Rubin, D. (2003). Bayesian Data Analysis, 2nd Edition, Chapman & Hall.
  - ▶ Liu, J. (2001). Monte Carlo Strategies in Scientific Computing, Springer-Verlag.
  - ► Lange, K. (2002). Numerical Analysis for Statisticians, Springer-Verlag, 2nd Edition.
  - ► Hastie, T., Tibshirani, R. and Friedman, J. (2009). The Elements of Statistical Learning, 2nd Edition, Springer.
  - ► Goodfellow, I., Bengio, Y. and Courville, A. (2016). Deep Learning, MIT Press.



- ► Optimization Methods
  - ► Gradient Methods
  - ► Expectation Maximization
- ► Approximate Bayesian Inference Methods
  - ► Markov chain Monte Carlo
  - ► Variational Inference
  - ► Scalable Approaches
- ▶ Applications in Machine Learning & Related Fields
  - ► Variational Autoencoder
  - ► Generative Adversarial Networks
  - ► Flow-based Generative Models
  - ► Bayesian Phylogenetic Inference



Familiar with at least one programming language (with python preferred!).

- ▶ All class assignments will be in python (and use numpy).
- ▶ You can find a good Python tutorial at

http://www.scipy-lectures.org/

You may find a shorter python+numpy tutorial useful at http://cs231n.github.io/python-numpy-tutorial/

Familiar with the following subjects

- ▶ Probability and Statistical Inference
- ► Stochastic Processes



- ▶ 4 Problem Sets:  $4 \times 15\% = 60\%$
- ► Final Course Project: 40%
  - ightharpoonup up to 4/5 people for each team
  - ► Teams should be formed by the end of week 4
  - ► Midterm proposal: 5%
  - ► Oral presentation: 10%
  - ► Final write-up: 25%
- ► Late policy
  - ▶ 7 free late days, use them in your ways
  - ► Afterward, 25% off per late day
  - ► No more than 3 late days per PS
  - ▶ Does not apply to Final Course Project
- ► Collaboration policy
  - ► Finish your work independently, verbal discussion allowed



- ▶ Structure your project exploration around a general problem type, algorithm, or data set, but should explore around your problem, testing thoroughly or comparing to alternatives.
- ▶ Present a project proposal that briefly describe your teams' project concept and goals in one slide in class on 11/10.
- ► There will be in class project presentation at the end of the term. Not presenting your projects will be taken as voluntarily giving up the opportunity for the final write-ups.
- ► Turn in a write-up (< 10 pages) describing your project and its outcomes, similar to a research-level publication.



► A brief overview of statistical approaches

▶ Basic concepts in statistical computing















Land to the first of the first







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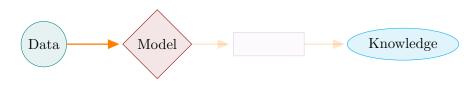


Linear Models

Neural Networks

Bayesian Nonparametric Models

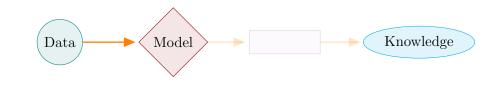
Generalized Linear Models



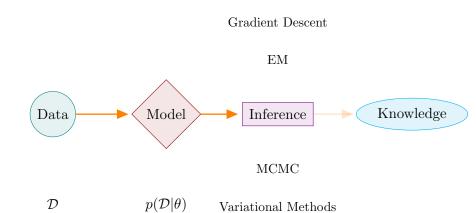
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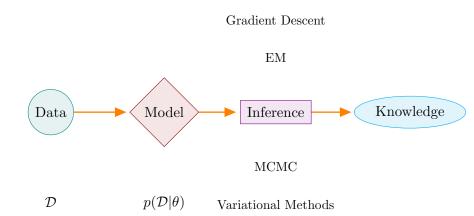


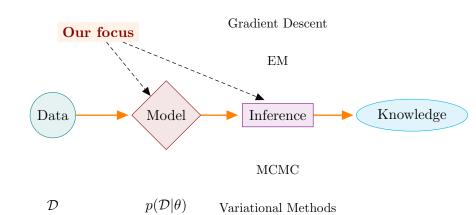
 $\mathcal{D}$ 



 $p(\mathcal{D}|\theta)$ 







"All models are wrong, but some are useful."

George E. P. Box

Models are used to describe the data generating process, hence prescribe the probabilities of the observed data  $\mathcal{D}$ 

$$p(\mathcal{D}|\theta)$$

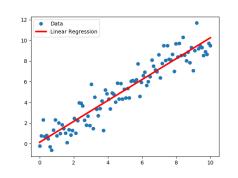
also known as the **likelihood**.



**Data**: 
$$\mathcal{D} = \{(x_i, y_i)\}_{i=1}^n$$

## Model:

$$Y = X\theta + \epsilon, \ \epsilon \sim \mathcal{N}(0, \sigma^2 I_n)$$
$$\Rightarrow Y \sim \mathcal{N}(X\theta, \sigma^2 I_n)$$



$$p(Y|X,\theta) = (2\pi\sigma^2)^{-n/2} \exp\left(-\frac{\|Y - X\theta\|_2^2}{2\sigma^2}\right)$$



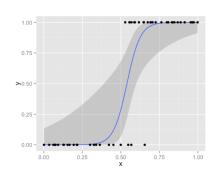
### Data:

$$\mathcal{D} = \{(x_i, y_i)\}_{i=1}^n, \ y_i \in \{0, 1\}$$

### Model:

$$Y \sim \text{Bernoulli}(p)$$

$$p = \frac{1}{1 + \exp(-X\theta)}$$



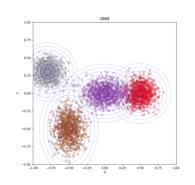
$$p(Y|X,\theta) = \prod_{i=1}^{n} p_i^{y_i} (1-p_i)^{1-y_i}$$

Data: 
$$\mathcal{D} = \{y_i\}_{i=1}^n, \ y_i \in \mathbb{R}^d$$

### Model:

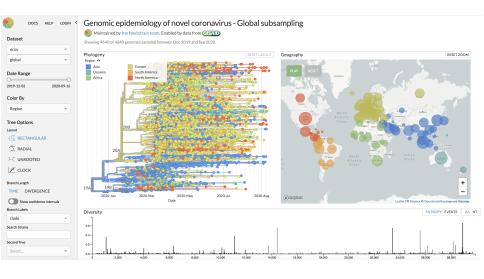
$$y|Z=z \sim \mathcal{N}(\mu_z, \sigma_z^2 I_d)$$

 $Z \sim \text{Categorical}(\alpha)$ 



$$p(Y|\mu, \sigma, \alpha) = \prod_{i=1}^{n} \sum_{k=1}^{K} \alpha_k (2\pi\sigma_k^2)^{(-d/2)} \exp\left(-\frac{\|y_i - \mu_k\|_2^2}{2\sigma_k^2}\right)$$



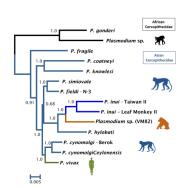




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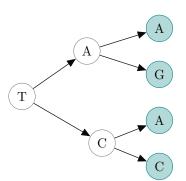




**Model**: Phylogenetic tree:  $(\tau, q)$ . Substitution model:

- ▶ stationary distribution:  $\eta(a_{\rho})$ .
- ► transition probability:

$$p(a_u \to a_v | q_{uv}) = P_{a_u a_v}(q_{uv})$$

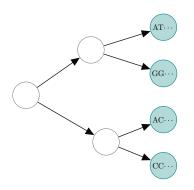


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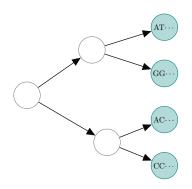
$$p(Y|\tau,q) = \prod_{i=1}^{n} \sum_{a^{i}} \eta(a_{\rho}^{i}) \prod_{(u,v) \in E(\tau)} P_{a_{u}^{i} a_{v}^{i}}(q_{uv})$$

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Substitution model:

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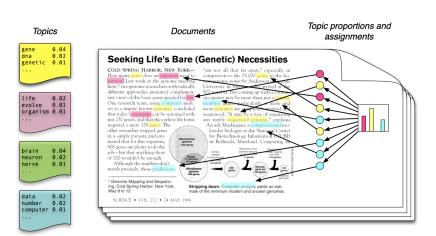
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where  $a^i$  agree with  $y_i$  at the tips

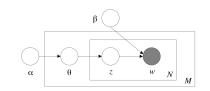




- ► Each topic is a distribution over words
- ▶ Documents exhibit multiple topics

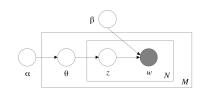


**Data**: a corpus  $\mathcal{D} = \{\boldsymbol{w}_i\}_{i=1}^M$ 



**Model**: for each document w in  $\mathcal{D}$ ,

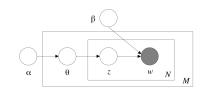
**Data**: a corpus  $\mathcal{D} = \{\boldsymbol{w}_i\}_{i=1}^M$ 



**Model**: for each document w in  $\mathcal{D}$ ,

• choose a mixture of topics  $\theta \sim \text{Dir}(\alpha)$ 

**Data**: a corpus  $\mathcal{D} = \{\boldsymbol{w}_i\}_{i=1}^M$ 

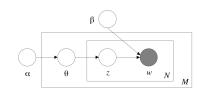


**Model**: for each document w in  $\mathcal{D}$ ,

- choose a mixture of topics  $\theta \sim \text{Dir}(\alpha)$
- $\blacktriangleright$  for each of the N words  $w_n$ ,

$$z_n \sim \text{Multinomial}(\theta), \quad w_n|z_n, \beta \sim p(w_n|z_n, \beta)$$

**Data**: a corpus 
$$\mathcal{D} = \{\boldsymbol{w}_i\}_{i=1}^M$$



**Model**: for each document w in  $\mathcal{D}$ ,

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$$z_n \sim \text{Multinomial}(\theta), \quad w_n|z_n, \beta \sim p(w_n|z_n, \beta)$$

$$p(\mathcal{D}|\alpha,\beta) = \prod_{d=1}^{M} \int p(\theta_d|\alpha) \prod_{n=1}^{N_d} \sum_{z_{dn}} p(z_{dn}|\theta_d) p(w_{dn}|z_{dn},\beta) d\theta_d$$

Many well-known distributions take the following form

$$p(y|\theta) = h(y) \exp (\phi(\theta) \cdot T(y) - A(\theta))$$

- $\blacktriangleright \phi(\theta)$ : natural/canonical parameters
- ightharpoonup T(y): sufficient statistics
- $ightharpoonup A(\theta)$ : log-partition function

$$A(\theta) = \log \left( \int_{y} h(y) \exp(\phi(\theta) \cdot T(y)) \ dy \right)$$

 $Y \sim \text{Bernoulli}(\theta)$ :

$$p(y|\theta) = \theta^y (1-\theta)^{1-y}$$
$$= \exp\left(\log\left(\frac{\theta}{1-\theta}\right)y + \log(1-\theta)\right)$$

$$ightharpoonup T(y) = y$$

$$A(\theta) = -\log(1 - \theta) = \log(1 + e^{\phi(\theta)})$$

► 
$$h(y) = 1$$

$$Y \sim \mathcal{N}(\mu, \sigma^2)$$
:

$$p(y|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2\sigma^2}(y-\mu)^2\right)$$
$$= \frac{1}{\sqrt{2\pi}} \exp\left(\frac{\mu}{\sigma^2}y - \frac{1}{2\sigma^2}y^2 - \frac{\mu^2}{2\sigma^2} - \log\sigma\right)$$

$$\bullet$$
  $\phi(\theta) = \left[\frac{\mu}{\sigma^2}, -\frac{1}{2\sigma^2}\right]^T$ 

$$\blacktriangleright \ T(y) = [y,y^2]^T$$

$$A(\theta) = \frac{\mu^2}{2\sigma^2} + \log \sigma$$

$$h(y) = \frac{1}{\sqrt{2\pi}}$$

 $Y = \{y_i\}_{i=1}^n, y_i \sim p(y_i|\theta), \text{ the Log-likelihood }$ 

$$L(\theta; Y) = \sum_{i=1}^{n} \log p(y_i | \theta)$$

The gradient of L with respect to  $\theta$  is called the **score** 

$$s(\theta) = \frac{\partial L}{\partial \theta}$$

The expected value of the score is zero

$$\mathbb{E}(s) = \sum_{i=1}^{n} \int \frac{\partial \log p(y_i|\theta)}{\partial \theta} p(y_i|\theta) \ dy_i = \sum_{i=1}^{n} \frac{\partial}{\partial \theta} \int p(y_i|\theta) \ dy_i = 0$$

**Fisher information** is the variance of the score.

$$\mathcal{I}(\theta) = \mathbb{E}(ss^T)$$

Under mild assumptions (e.g., exponential families),

$$\mathcal{I}(\theta) = -\mathbb{E}\left(\frac{\partial^2 L}{\partial \theta \partial \theta^T}\right)$$

Intuitively, Fisher information is a measure of the curvature of the Log-likelihood function. Therefore, it reflects the sensitivity of model about the parameter at its current value. ▶ Kullback-Leibler divergence or KL divergence is a measure of statistical distance between two distributions p(x) and q(x)

$$D_{KL}(q||p) = \int q(x) \log \frac{q(x)}{p(x)} dx$$

► KL divergence is non-negative

$$D_{KL}(q||p) = -\int q(x)\log\frac{p(x)}{q(x)} \ge -\log\int p(x) \ dx = 0$$

► Consider a family of distributions  $p(x|\theta)$ , Fisher information is Hessian of KL-divergence between two distributions  $p(x|\theta)$  and  $p(x|\theta')$  with respect to  $\theta'$  at  $\theta' = \theta$ 

$$\nabla_{\theta'}^2 D_{KL} \left( p(x|\theta) || p(x|\theta') \right) |_{\theta' = \theta} = \mathcal{I}(\theta)$$



$$\hat{\theta}_{MLE} = \underset{\theta}{\arg\max} L(\theta) \approx \underset{\theta}{\arg\max} \mathbb{E}_{y \sim p_{data}} \log \frac{p(y|\theta)}{p_{data}(y)}$$
$$= \underset{\theta}{\arg\min} D_{KL}(p_{data}(y)||p(y|\theta))$$

- ▶ Consistency. Under weak regularity condition,  $\hat{\theta}_{MLE}$  is consistent:  $\hat{\theta}_{MLE} \to \theta_0$  in probability as  $n \to \infty$ , where  $\theta_0$  is the "true" parameter
- ► Asymptotical Normality.

$$\hat{\theta}_{MLE} - \theta_0 \to \mathcal{N}(0, \mathcal{I}^{-1}(\theta_0))$$

See Rao 1973 for more details.



$$L(\theta; y_1, \dots, y_n) = \sum_{i=1}^n y_i \log \theta - n\theta - \sum_{i=1}^n \log y_i!$$

$$s(\theta) = \frac{\sum_{i=1}^n y_i}{\theta} - n, \quad \mathcal{I}(\theta) = \frac{n}{\theta}$$

$$\hat{\theta}_{MLE} = \arg\max_{\theta} \sum_{i=1}^n y_i \log \theta - n\theta = \frac{\sum_{i=1}^n y_i}{n}$$

By the Law of large numbers

$$\hat{\theta}_{MLE} \xrightarrow{p} \theta_0$$

By central limit theorem

$$\hat{\theta}_{MLE} - \theta_0 \xrightarrow{d} \mathcal{N}\left(0, \frac{\theta_0}{n}\right)$$



- ► Can we find an unbiased estimator with smaller variance than  $\mathcal{I}^{-1}(\theta_0)$ ?
- ▶ Cramér-Rao Lower Bound: For any unbiased estimator  $\hat{\theta}$  of  $\theta_0$  based on independent observations following the true distribution, the variance of the estimator is bounded by the reciprocal of the Fisher information

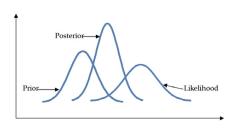
$$\operatorname{Var}(\hat{\theta}) \ge \frac{1}{\mathcal{I}(\theta_0)}$$

Sketch of proof: Consider a general estimator T = t(X) with  $\mathbb{E}(T) = \psi(\theta_0)$ . Let s be the score function,

$$\mathbb{C}\mathrm{ov}(T,s) = \mathbb{E}(Ts) = \psi'(\theta_0) \Rightarrow \mathbb{V}\mathrm{ar}(T) \ge \frac{[\psi'(\theta_0)]^2}{\mathbb{V}\mathrm{ar}(s)} = \frac{[\psi'(\theta_0)]^2}{\mathcal{I}(\theta_0)}$$



In Bayesian statistics, besides specifying a model  $p(y|\theta)$  for the observed data, we also specify our **prior**  $p(\theta)$  for the model parameters.



Bayes rule for inverse probability

$$p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta) \cdot p(\theta)}{p(\mathcal{D})} \propto p(\mathcal{D}|\theta) \cdot p(\theta)$$

known as the **posterior**.



- uncertainty quantification, provides more useful information
- ightharpoonup reducing overfitting. Regularization  $\iff$  Prior.

## Prediction

$$p(x|\mathcal{D}) = \int p(x|\theta, \mathcal{D})p(\theta|\mathcal{D})d\theta$$

## **Model Comparison**

$$p(m|\mathcal{D}) = \frac{p(\mathcal{D}|m)p(m)}{p(\mathcal{D})}$$

$$p(\mathcal{D}|m) = \int p(\mathcal{D}|\theta, m) p(\theta|m) d\theta$$

- ▶ Subjective Priors. Priors should reflect our beliefs as well as possible. They are subjective, but not arbitrary.
- ▶ **Hierarchical Priors**. Priors of multiple levels.

$$p(\theta) = \int p(\theta|\alpha)p(\alpha) d\alpha$$
$$= \int p(\theta|\alpha) d\alpha \int p(\alpha|\beta)p(\beta) d\beta$$

▶ Conjugate Priors. Priors that ease computation, often used to facilitate the development of inference and parameter estimation algorithms.



- ▶ Conjugacy: prior  $p(\theta)$  and posterior  $p(\theta|Y)$  belong to the same family of distribution
- ► Exponential family

$$p(Y|\theta) \propto \exp\left(\phi(\theta) \cdot \sum_{i} T(y_i) - nA(\theta)\right)$$

► Conjugate prior

$$p(\theta) \propto \exp(\phi(\theta) \cdot \nu - \eta A(\theta))$$

► Posterior

$$p(\theta|Y) \propto \exp\left(\phi(\theta) \cdot (\nu + \sum_{i} T(y_i)) - (n+\eta)A(\theta)\right)$$

**Data**:  $\mathcal{D} = \{x_i\}_{i=1}^m$ . For each x in  $\mathcal{D}$ 

$$p(\boldsymbol{x}|\theta) \propto \exp\left(\sum_{k=1}^{K} x_k \log \theta_k\right)$$

Use  $Dir(\alpha)$  as the conjugate prior

$$p(\theta) \propto \exp\left(\sum_{k=1}^{K} (\alpha_k - 1) \log \theta_k\right)$$

$$p(\theta|\mathcal{D}) \propto \exp\left(\sum_{k=1}^{K} \left(\alpha_k - 1 + \sum_{i=1}^{M} x_{ik}\right) \log \theta_k\right)$$



Consider random variables  $\{X_t\}, t = 0, 1, \dots$  with state space  $\mathcal{S}$ 

## Markov Property

$$p(X_{n+1} = x | X_0 = x_0, \dots, X_n = x_n) = p(X_{n+1} = x | X_n = x_n)$$

Transition Probability

$$P_{ij}^{n} = p(X_{n+1} = j | X_n = i), \quad i, j \in \mathcal{S}.$$

A Markov chain is called *time homogeneous* if  $P_{ij}^n = P_{ij}, \forall n$ .

A Markov chain is governed by its transition probability matrix.



► Stationary Distribution.

$$\pi^T P = \pi^T$$
.

▶ Ergodic Theorem. If the Markov chain is irreducible and aperiodic, with stationary distribution  $\pi$ , then

$$X_n \xrightarrow{d} \pi$$

and for any function h

$$\frac{1}{n} \sum_{t=1}^{n} h(X_t) \to \mathbb{E}_{\pi} h(X), \quad n \to \infty$$

given  $\mathbb{E}_{\pi}|h(X)|$  exists.

What's Next?

- ▶ In general, finding MLE and posterior analytically is difficult. We almost always have to resort to computational methods.
- ▶ In this course, we'll discuss a variety of computational techniques for numerical optimization and integration, approximate Bayesian inference methods, with applications in statistical machine learning, computational biology and other related field.

References 35/35

- ▶ J. Felsenstein. Evolutionary trees from DNA sequences: a maximum likelihood approach. J. Mol. Evol. 17, 368–376 (1981)
- ▶ D. M. Blei, A. Y. Ng, and M. I. Jordan. Latent dirichlet allocation. JMLR 3, 2003.
- ► C. R. Rao. Linear Statistical Inference and its Applications. 2nd edition. New York: Wiley, 1973.
- ► S. M. Ross. Introduction to Probability Models, 7th ed. Academic, 2000.

