Modern Computational Statistics

Lecture 14: Stochastic Variational Inference



Cheng Zhang

School of Mathematical Sciences, Peking University

November 11, 2019

- ▶ Mean-field VI can be slow when the data size is large.
- ► Moreover, the conditional conjugacy required by mean-field VI greatly reduces the general applicability of the method.
- ► Fortunately, as an optimization approach, VI allows us to easily combine it with various scalable optimization methods.
- ▶ In this lecture, we will introduce some of the recent advancements on scalable variational inference, both for mean-field VI and more general VI.



► A generic class of models

$$p(\beta, z, x) = p(\beta) \prod_{i=1}^{n} p(z_i, x_i | \beta)$$

► The mean-field approximation

$$q(\beta, z) = q(\beta|\lambda) \prod_{i=1}^{n} q(z_i|\phi_i)$$

Coordinate ascent could be data-inefficient

$$\lambda^* = \mathbb{E}_{q(z)}(\eta_g(x, z)), \quad \phi_i^* = \mathbb{E}_{q(\beta)}(\eta_\ell(x_i, \beta))$$

- ► Requires local computation for each data points.
- ▶ Aggregate these computation to update the global parameter.

 \blacktriangleright Recall that the λ -ELBO (update to a constant) is

$$L(\lambda) = \nabla_{\lambda} A_g(\lambda)^{\top} \left(\alpha + \sum_{i=1}^{n} \mathbb{E}_{\phi_i} (T(z_i, x_i)) - \lambda \right) + A_g(\lambda)$$

▶ Differentiating this w.r.t. λ yields

$$\nabla_{\lambda} L(\lambda) = \nabla_{\lambda}^{2} A_{g}(\lambda) \left(\alpha + \sum_{i=1}^{n} \mathbb{E}_{\phi_{i}}(T(z_{i}, x_{i})) - \lambda \right)$$

► Similarly

$$\nabla_{\phi_i} L(\phi_i) = \nabla_{\phi_i}^2 A_{\ell}(\phi_i) \left(\mathbb{E}_{\lambda}(\eta_{\ell}(x_i, \beta)) - \phi_i \right)$$



▶ The gradient of f at λ , $\nabla_{\lambda} f(\lambda)$ points in the same direction as the solution to

$$\underset{d\lambda}{\arg\max} f(x+d\lambda), \quad s.t. \ \|d\lambda\|^2 \le \epsilon^2$$

for sufficiently small ϵ .

- ▶ The gradient direction implicitly depends on the Euclidean distance, which might not capture the distance between the parameterized probability distribution $q(\beta|\lambda)$.
- ▶ We can use *natural gradient* instead, which points in the same direction as the solution to

$$\arg\max_{d\lambda} f(x+d\lambda), \quad s.t. \ \operatorname{D}_{\mathrm{KL}}^{\mathrm{sym}}(q(\beta|\lambda), q(\beta|\lambda+d\lambda)) \le \epsilon$$

for sufficiently small ϵ , where D_{KL}^{sym} is the symmetrized KL divergence.

▶ We manage the symmetrized KL divergence constraint with a Riemannian metric $G(\lambda)$

$$D_{\mathrm{KL}}^{\mathrm{sym}}(q(\beta|\lambda), q(\beta|\lambda + d\lambda)) \approx d\lambda^{\top} G(\lambda) d\lambda$$

as $d\lambda \to 0$. G is the **Fisher information** matrix of $q(\beta|\lambda)$

$$G(\lambda) = \mathbb{E}_{\lambda} \left((\nabla_{\lambda} \log q(\beta|\lambda)) (\nabla_{\lambda} \log q(\beta|\lambda))^{\top} \right)$$

► The natural gradient (Amari, 1998)

$$\hat{\nabla}_{\lambda} f(\lambda) \triangleq G(\lambda)^{-1} \nabla_{\lambda} f(\lambda)$$

• When $q(\beta|\lambda)$ is in the prescribed exponential family

$$G(\lambda) = \nabla_{\lambda}^2 A_g(\lambda)$$



► The natural gradient of the ELBO

$$\nabla_{\lambda}^{\text{nat}} L = \left(\alpha + \sum_{i=1}^{n} \mathbb{E}_{\phi_i} (T(z_i, x_i))\right) - \lambda$$
$$\nabla_{\phi_i}^{\text{nat}} L = \mathbb{E}_{\lambda} (\eta_{\ell}(x_i, \beta)) - \phi_i$$

Classical coordinate ascent can be viewed as natural gradient descent with step size one

▶ Use the noisy natural gradient instead

$$\hat{\nabla}_{\lambda}^{\text{nat}}L(\lambda) = \alpha + n\mathbb{E}_{\phi_j}(T(z_j, x_j)) - \lambda, \quad j \sim \text{Uniform}(1, \dots, n)$$

- ► This is a good noisy gradient
 - ► The expectation is the exact gradient (unbiased).
 - ▶ Depends merely on optimized local parameters (cheap).



Input: data \mathbf{x} , model $p(\beta, \mathbf{z}, \mathbf{x})$.

Initialize λ randomly. Set ρ_t appropriately.

repeat

Sample $j \sim \text{Unif}(1, ..., n)$.

Set local parameter $\phi \leftarrow \mathbb{E}_{\lambda} [\eta_{\ell}(\beta, x_j)].$

Set intermediate global parameter

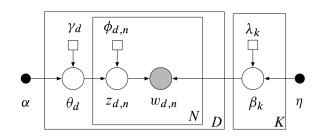
$$\hat{\lambda} = \alpha + n \mathbb{E}_{\phi}[t(Z_j, x_j)].$$

Set global parameter

$$\lambda = (1 - \rho_t)\lambda + \rho_t \hat{\lambda}.$$

until forever





Classic Coordinate Ascent

$$\phi_{d,n,k} \propto \exp\left(\mathbb{E}(\log \theta_{d,k}) + \mathbb{E}(\log \beta_{k,w_{d,n}})\right)$$

$$\gamma_d = \alpha + \sum_{n=1}^N \phi_{d,n}, \quad \lambda_k = \eta + \sum_{d=1}^D \sum_{n=1}^N \phi_{d,n,k} w_{d,n}$$



- \triangleright Sample a document w_d uniform from the data set
- Estimate the local variational parameters using the current topics. For $n=1,\ldots,N$

$$\phi_{d,n,k} \propto \exp\left(\mathbb{E}(\log \theta_{d,k}) + \mathbb{E}(\log \beta_{k,w_{d,n}})\right), \quad k = 1, \dots, K$$

$$\gamma_d = \alpha + \sum_{n=1}^{N} \phi_{d,n}$$

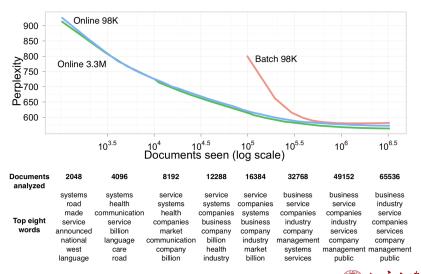
► Form the intermediate topics from those local parameters for noisy natural gradient

$$\hat{\lambda}_k = \eta + D \sum_{n=1}^{N} \phi_{d,n,k} w_{d,n}, \quad k = 1, \dots, K$$

▶ Update topics using noisy natural gradient

$$\lambda = (1 - \rho_t)\lambda + \rho_t \hat{\lambda}$$







- ▶ Mean-field VI works for conjugate-exponential models, where the local optimal has closed-form solution.
- ► For more general models, we may not have this conditional conjugacy
 - ► Nonlinear Time Series Models
 - ► Deep Latent Gaussian Models
 - ► Generalized Linear Models
 - ► Stochastic Volatility Models
 - ► Bayesian Neural Networks
 - ► Sigmoid Belief Network
- ▶ While we may derive a model specific bound for each of these models (Knowles and Minka, 2011; Paisley et al., 2012), it would be better if there is a solution that does not entail model specific work.



► The logistic regression model

$$y_i \sim \text{Bernoulli}(p_i), \ p_i = \frac{1}{1 + \exp(-x_i^{\top} \beta)}. \quad \beta \sim \mathcal{N}(0, I_d)$$

► The mean-field approximation

$$q(\beta) = \prod_{j=1}^{d} \mathcal{N}(\beta_j | \mu_j, \sigma_j^2)$$

► The ELBO is

$$L(\mu, \sigma^2) = \mathbb{E}_q(\log p(\beta) + \log p(y|x, \beta) - \log q(\beta))$$



$$\begin{split} L(\mu, \sigma^2) &= \mathbb{E}_q(\log p(\beta) - \log q(\beta) + \log p(y|x, \beta)) \\ &= -\frac{1}{2} \sum_{j=1}^d (\mu_j^2 + \sigma_j^2) + \frac{1}{2} \sum_{j=1}^d \log \sigma_j^2 + \mathbb{E}_q \log p(y|x, \beta) + \text{Const} \\ &= \frac{1}{2} \sum_{j=1}^d (\log \sigma_j^2 - \mu_j^2 - \sigma_j^2) + Y^\top X \mu - \mathbb{E}_q(\log(1 + \exp(X\beta))) \end{split}$$

- ▶ We can not compute the expectation term
- ► This hides the objective dependence on the variational parameters, making it hard to directly optimize.



- ▶ Let $p(x, \theta)$ be the joint probability (i.e., the posterior up to a constant), and $q_{\phi}(\theta)$ be our variational approximation
- ► The ELBO is

$$L(\phi) = \mathbb{E}_q(\log p(x, \theta) - \log q_{\phi}(\theta))$$

- ► Instead of requiring a closed-form lower bound and differentiating afterwards, we can take derivatives directly
- As shown later, this leads to a stochastic optimization approach that handles massive data sets as well.

► Compute the gradient

$$\nabla_{\phi} L = \nabla_{\phi} \mathbb{E}_{q} (\log p(x, \theta) - \log q_{\phi}(\theta))$$

$$= \int \nabla_{\phi} q_{\phi}(\theta) (\log p(x, \theta) - \log q_{\phi}(\theta)) d\theta$$

$$- q_{\phi}(\theta) \nabla_{\phi} \log q_{\phi}(\theta) d\theta$$

$$= \int q_{\phi}(\theta) \nabla_{\phi} \log q_{\phi}(\theta) (\log p(x, \theta) - \log q_{\phi}(\theta))$$

$$- q_{\phi}(\theta) \nabla_{\phi} \log q_{\phi}(\theta) d\theta$$

$$= \mathbb{E}_{q} (\nabla_{\phi} \log q_{\phi}(\theta) (\log p(x, \theta) - \log q_{\phi}(\theta) - 1))$$
Using $\nabla_{\phi} \log q_{\phi} \theta = \frac{\nabla_{\phi} q_{\phi}(\theta)}{q_{\phi}(\theta)}$

► Recall that

$$\nabla_{\phi} L = \mathbb{E}_q \left(\nabla_{\phi} \log q_{\phi}(\theta) (\log p(x, \theta) - \log q_{\phi}(\theta) - 1) \right)$$

▶ Note that

$$\mathbb{E}_q \nabla_\phi \log q_\phi(\theta) = 0$$

► We can simplify the gradient as follows

$$\nabla_{\phi} L = \mathbb{E}_q \left(\nabla_{\phi} \log q_{\phi}(\theta) (\log p(x, \theta) - \log q_{\phi}(\theta)) \right)$$

► This is known as score function estimator or REINFORCE gradients (Williams, 1992; Ranganath et al., 2014; Minh et al., 2014)



$$\nabla_{\phi} L = \mathbb{E}_q \left(\nabla_{\phi} \log q_{\phi}(\theta) (\log p(x, \theta) - \log q_{\phi}(\theta)) \right)$$

► Unbiased stochastic gradients via Monte Carlo!

$$\frac{1}{S} \sum_{s=1}^{S} \nabla_{\phi} \log q_{\phi}(\theta_s) (\log p(x, \theta_s) - \log q_{\phi}(\theta_s)), \quad \theta_s \sim q_{\phi}(\theta)$$

- ► The requirements for inference
 - ightharpoonup Sampling from $q_{\phi}(\theta)$
 - ightharpoonup Evaluating $\nabla_{\phi} \log q_{\phi}(\theta)$
 - ightharpoonup Evaluating $\log p(x,\theta)$ and $\log q_{\phi}(\theta)$
- ► This is called **Black Box Variational Inference** (BBVI): no model specific work! (Ranganath et al., 2014)



Algorithm 1: Basic Black Box Variational Inference

Input: Model $\log p(\mathbf{x}, \mathbf{z})$,

Variational approximation $q(\mathbf{z}; \mathbf{v})$

Output : Variational Parameters: ν

while not converged do

$$\mathbf{z}[s] \sim q$$
 // Draw S samples from q $\rho = t$ -th value of a Robbins Monro sequence $\mathbf{v} = \mathbf{v} + \rho \frac{1}{S} \sum_{s=1}^{S} \nabla_{\mathbf{v}} \log q(\mathbf{z}[s]; \mathbf{v}) (\log p(\mathbf{x}, \mathbf{z}[s]) - \log q(\mathbf{z}[s]; \mathbf{v}))$ $t = t + 1$

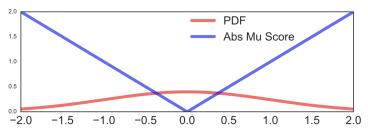
end

Ranganath et al., 2014



Variance of the gradient can be a problem

$$\operatorname{Var}_{q_{\phi}(\theta)} = \mathbb{E}_{q} \left((\nabla_{\phi} \log q_{\phi}(\theta) (\log p(x, \theta) - \log q_{\phi}(\theta)) - \nabla_{\phi} L)^{2} \right)$$



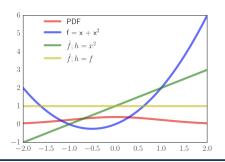
Adapted from Blei, Ranganath and Mohamed

- ▶ magnitude of $\log p(x,\theta) \log q_{\phi}(\theta)$ varies widely
- ► rare values sampling
- ▶ too much variance to be useful



- ➤ To make BBVI work in practice, we need methods to reduce the variance of naive Monte Carlo estimates
- ▶ Control Variates. To reduce the variance of Monte Carlo estimates of $\mathbb{E}(f(x))$, we replace f with \hat{f} such that $\mathbb{E}(\hat{f}(x)) = \mathbb{E}(f(x))$. A general class

$$\hat{f}(x) = f(x) - a(h(x) - \mathbb{E}h(x))$$



- ightharpoonup a can be chosen to minimize the variance.
- \blacktriangleright h is a function of our choice. Good h have high correlation with the original function f.



$$\hat{f}(x) = f(x) - a(h(x) - \mathbb{E}h(x))$$

- ightharpoonup For variational inference, we need h functions with known q expectation
- ▶ A commonly used one is $h(\theta) = \nabla_{\phi} \log q_{\phi}(\theta)$, where

$$\mathbb{E}_q(\nabla_\phi \log q_\phi(\theta)) = 0, \quad \forall q$$

▶ The variance of \hat{f} is

$$Var(\hat{f}) = Var(f) + a^2 Var(h) - 2aCov(f, h)$$

and the optimal scaling is $a^* = \text{Cov}(f,h)/\text{Var}(h)$. In practice this can be estimated using the empirical variance and covariance on the samples

Baseline 23/32

▶ When $h(\theta) = \nabla_{\phi} \log q_{\phi}(\theta)$, the control variate gradient is

$$\nabla_{\phi} L = \mathbb{E}_q \left(\nabla_{\phi} \log q_{\phi}(\theta) (\log p(x, \theta) - \log q_{\phi}(\theta) - \mathbf{a}) \right)$$

and a is called a **baseline**.

- \blacktriangleright Baselines can be constant, or input-dependent a(x).
- ▶ While we can estimate the baseline using the samples as before, people often use a *model-agnostic* baseline to *centre* the learning signal (Minh and Gregor, 2014)

$$\rho = \operatorname*{arg\,min}_{\rho} \mathbb{E}_{q} (\ell(x, \theta, \phi) - a_{\rho}(x))^{2}$$

where the learning signal is

$$\ell(x, \theta, \phi) = \log p(x, \theta) - \log q_{\phi}(\theta)$$



- ▶ We can use Rao-Blackwellization to reduce the variance by integrating out some random variables.
- ► Consider the mean-field variational family

$$q(\theta) = \prod_{i=1}^{d} q_i(\theta_i | \phi_i)$$

Let $q_{(i)}$ be the distribution of variables that depend on the ith variable (i.e., the Markov blanket of θ_i and θ_i), and let $p_i(x,\theta_{(i)})$ be the terms in the joint probability that depend on those variables.

$$\nabla_{\phi_i} L = \mathbb{E}_{q_{(i)}} \left(\nabla_{\phi_i} \log q_i(\theta_i | \phi_i) (\log p_i(x, \theta_{(i)}) - \log q_i(\theta_i | \phi_i)) \right)$$

► This can be combined with control variates.



- ► Another commonly used variance reduction technique is the reparameterization trick (Kingma et al., 2014; Rezende et al., 2014)
- ► The Reparameterization

$$\theta = g_{\phi}(\epsilon), \ \epsilon \sim q_{\epsilon}(\epsilon) \implies \theta \sim q_{\phi}(\theta)$$

► Example:

$$\theta = \epsilon \sigma + \mu, \ \epsilon \sim \mathcal{N}(0, 1) \iff \theta \sim \mathcal{N}(\mu, \sigma^2)$$

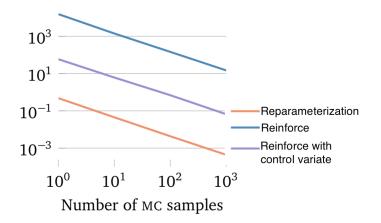
► Compute the gradient via the reparameterization trick

$$\nabla_{\phi} L = \nabla_{\phi} \mathbb{E}_{q_{\phi}(\theta)} (\log p(x, \theta) - \log q_{\phi}(\theta))$$

$$= \nabla_{\phi} \mathbb{E}_{q_{\epsilon}(\epsilon)} (\log p(x, g_{\phi}(\epsilon)) - \log q_{\phi}(g_{\phi}(\epsilon)))$$

$$= \mathbb{E}_{q_{\epsilon}(\epsilon)} \nabla_{\phi} (\log p(x, g_{\phi}(\epsilon)) - \log q_{\phi}(g_{\phi}(\epsilon)))$$





Kucukelbir et al., 2016



Score Function

- ▶ Differentiates the density $\nabla_{\phi}q_{\phi}(\theta)$
- Works for general models, including both discrete and continuous models.
- Works for large class of variational approximations
- ► May suffer from large variance

Reparameterization

- ▶ Differentiates the function $\nabla_{\phi}(\log p(x,\theta) \log q_{\phi}(\theta))$
- Requires differentiable models
- ► Requires variational approximation to have form $\theta = g_{\phi}(\epsilon)$
- ► Better behaved variance in general



- ► Scale up previous stochastic variational inference methods to large data set via **data subsampling**.
- ► Replace the log joint distribution with unbiased stochastic estimates

$$\log p(x,\theta) \simeq \log p(\theta) + \frac{n}{m} \sum_{i=1}^{m} \log p(x_{t_i}|\theta), \quad m \ll n$$

► Example: score function estimator

$$\hat{\nabla}_{\phi} L = \frac{1}{S} \sum_{s=1}^{S} \nabla_{\phi} \log q_{\phi}(\theta_s) \left(\log p(\theta_s) + \frac{n}{m} \sum_{i=1}^{m} \log p(x_{t_i} | \theta_s) - \log q_{\phi}(\theta_s) \right), \quad \theta_s \sim q_{\phi}(\theta)$$

Summary 29/32

► When the data size is large, we can use **stochastic optimization** to scale up VI.

- ► For conditional exponential models, we can use noisy natural gradient.
- ▶ For general models, naive stochastic gradient estimators may have large variance, variance reduction techniques are often required.
 - ► Score function estimator (for both discrete and continuous latent variable)
 - ► The reparameterization trick (for continuous variable, and requires reparameterizable variational family)
- ▶ We can also combine score function estimators with the reparameterization trick for more general and robust stochastic gradient estimators (Ruiz et al., 2016)



References 30/32

► S. Amari. Natural gradient works efficiently in learning. Neural computation, 10(2):251–276, 1998.

- ► Hoffman, M., Blei, D., Wang, C., and Paisley, J. (2013). Stochastic variational inference. Journal of Machine Learning Research, 14:1303–1347.
- ▶ D. Knowles and T. Minka. Non-conjugate variational message passing for multinomial and binary regression. In Advances in Neural Information Processing Systems, 2011.
- ▶ J. Paisley, D. Blei, and M. Jordan. Variational Bayesian inference with stochastic search. International Conference in Machine Learning, 2012.



References 31/32

▶ Williams, R. J. (1992). Simple statistical gradient-following algorithms for connectionist reinforcement learning. In Machine Learning, pages 229–256.

- ▶ R. Ranganath, S. Gerrish, and D. Blei. Black box variational inference. In Artificial Intelligence and Statistics, 2014.
- ▶ Rezende, D. J., Mohamed, S., and Wierstra, D. (2014). Stochastic backpropagation and approximate inference in deep generative models. In International Conference on Machine Learning, pages 1278–1286.
- ▶ D. P. Kingma and M. Welling. Auto-encoding variational Bayes. In International Conference on Learning Representations, 2014.



References 32/32

▶ A. Mnih and K. Gregor. Neural variational inference and learning in belief networks. Advances in Neural Information Processing Systems, 2014.

► F. R. Ruiz, M. Titsias, and D. Blei. The generalized reparameterization gradient. Advances in Neural Information Processing Systems, 2016.

